# Schrödinger uncertainty relation, Wigner-Yanase-Dyson skew information and metric adjusted correlation measure 

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#### Abstract

In this paper, we give Schrödinger-type uncertainty relation using the Wigner-Yanase-Dyson skew information. In addition, we give Schrödinger-type uncertainty relation by use of a two-parameter extended correlation measure. We finally show the further generalization of Schrödinger-type uncertainty relation by use of the metric adjusted correlation measure. These results generalize our previous result in [Phys. Rev. A, Vol.82(2010), 034101].


Keywords : Trace inequality, Wigner-Yanase-Dyson skew information, Schrödinger uncertainty relation and metric adjusted correlation measure

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## 1 Introduction

In quantum information theory, one of the most important results is the strong subadditivity of von Neumann entropy [22]. This important property of von Neumann entropy can be proven by the use of Lieb's theorem [16] which gave a complete solution for the conjecture of the convexity of Wigner-Yanase-Dyson skew information. In addition, the uncertainty relation has been widely studied in quantum information theory [21, 31, 29]. In particular, the relations between skew information and uncertainty relation have been studied in $[17,4,8,9,7]$. Quantum Fisher information is also called monotone metric which was introduced by Petz [23] and the Wigner-Yanase-Dyson metric is connected to quantum Fisher information (monotone metric) as a special case. Recently, Hansen gave a further development of the notion of monotone metric, so-called metric adjusted skew information [12]. The Wigner-Yanase-Dyson skew information is also connected to the metric adjusted skew information as a special case. That is, the metric adjusted skew information gave a class including the Wigner-Yanase-Dyson skew information, while the monotone metric gave a class including the Wigner-Yanase-Dyson metric. In the paper [12], the metric adjusted correlation measure was also introduced as a generalization of the quantum covariance and correlation measure defined in [17]. Therefore there is a significance to give the relation among the Wigner-Yanase-Dyson skew information, metric adjusted correlation measure and uncertainty relation for the fundamental studies on quantum information theory.

[^0]We start from the Heisenberg uncertainty relation [13]:

$$
\begin{equation*}
V_{\rho}(A) V_{\rho}(B) \geq \frac{1}{4}|\operatorname{Tr}[\rho[A, B]]|^{2} \tag{1}
\end{equation*}
$$

for a quantum state (density operator) $\rho$ and two observables (self-adjoint operators) $A$ and $B$. The further stronger result was given by Schrödinger in [27, 28]:

$$
\begin{equation*}
V_{\rho}(A) V_{\rho}(B)-\left|\operatorname{Re}\left\{\operatorname{Cov}_{\rho}(A, B)\right\}\right|^{2} \geq \frac{1}{4}|\operatorname{Tr}[\rho[A, B]]|^{2}, \tag{2}
\end{equation*}
$$

where the covariance is defined by $\operatorname{Cov}_{\rho}(A, B) \equiv \operatorname{Tr}[\rho(A-\operatorname{Tr}[\rho A] I)(B-\operatorname{Tr}[\rho B] I)]$.
The Wigner-Yanase skew information represents a measure for non-commutativity between a quantum state $\rho$ and an observable $H$. Luo introduced the quantity $U_{\rho}(H)$ representing a quantum uncertainty excluding the classical mixture [18]:

$$
\begin{equation*}
U_{\rho}(H) \equiv \sqrt{V_{\rho}(H)^{2}-\left(V_{\rho}(H)-I_{\rho}(H)\right)^{2}} \tag{3}
\end{equation*}
$$

with the Wigner-Yanase skew information [32]:

$$
I_{\rho}(H) \equiv \frac{1}{2} \operatorname{Tr}\left[\left(i\left[\rho^{1 / 2}, H_{0}\right]\right)^{2}\right]=\operatorname{Tr}\left[\rho H_{0}^{2}\right]-\operatorname{Tr}\left[\rho^{1 / 2} H_{0} \rho^{1 / 2} H_{0}\right], \quad H_{0} \equiv H-\operatorname{Tr}[\rho H] I
$$

and then he successfully showed a new Heisenberg-type uncertainty relation on $U_{\rho}(H)$ in [18]:

$$
\begin{equation*}
U_{\rho}(A) U_{\rho}(B) \geq \frac{1}{4}|\operatorname{Tr}[\rho[A, B]]|^{2} \tag{4}
\end{equation*}
$$

As stated in [18], the physical meaning of the quantity $U_{\rho}(H)$ can be interpreted as follows. For a mixed state $\rho$, the variance $V_{\rho}(H)$ has both classical mixture and quantum uncertainty. Also, the Wigner-Yanase skew information $I_{\rho}(H)$ represents a kind of quantum uncertainty [19, 20]. Thus, the difference $V_{\rho}(H)-I_{\rho}(H)$ has a classical mixture so that we can regard that the quantity $U_{\rho}(H)$ has a quantum uncertainty excluding a classical mixture. Therefore it is meaningful and suitable to study an uncertainty relation for a mixed state by the use of the quantity $U_{\rho}(H)$.

Recently, a one-parameter extension of the inequality (4) was given in [33]:

$$
\begin{equation*}
U_{\rho, \alpha}(A) U_{\rho, \alpha}(B) \geq \alpha(1-\alpha)|\operatorname{Tr}[\rho[A, B]]|^{2} \tag{5}
\end{equation*}
$$

where

$$
U_{\rho, \alpha}(H) \equiv \sqrt{V_{\rho}(H)^{2}-\left(V_{\rho}(H)-I_{\rho, \alpha}(H)\right)^{2}}
$$

with the Wigner-Yanase-Dyson skew information $I_{\rho, \alpha}(H)$ is defined by

$$
I_{\rho, \alpha}(H) \equiv \frac{1}{2} \operatorname{Tr}\left[\left(i\left[\rho^{\alpha}, H_{0}\right]\right)\left(i\left[\rho^{1-\alpha}, H_{0}\right]\right)\right]=\operatorname{Tr}\left[\rho H_{0}^{2}\right]-\operatorname{Tr}\left[\rho^{\alpha} H_{0} \rho^{1-\alpha} H_{0}\right]
$$

It is notable that the convexity of $I_{\rho, \alpha}(H)$ with respect to $\rho$ was successfully proven by Lieb in [16]. The further generalization of the Heisenberg-type uncertainty relation on $U_{\rho}(H)$ has been given in [34] using the generalized Wigner-Yanase-Dyson skew information introduced in [3]. See also $[1,5,7,8]$ for the recent studies on skew informations and uncertainty relations.

Motivated by the fact that the Schrödinger uncertainty relation is a stronger result than the Heisenberg uncertainty relation, a new Schrödinger-type uncertainty relation for mixed states using Wigner-Yanase skew information was shown in [4]. That is, for a quantum state $\rho$ and two observables $A$ and $B$, we have

$$
\begin{equation*}
U_{\rho}(A) U_{\rho}(B)-\left|\operatorname{Re}\left\{\operatorname{Corr}_{\rho}(A, B)\right\}\right|^{2} \geq \frac{1}{4}|\operatorname{Tr}[\rho[A, B]]|^{2}, \tag{6}
\end{equation*}
$$

where the correlation measure [17] is defined by

$$
\operatorname{Corr}_{\rho}(X, Y) \equiv \operatorname{Tr}\left[\rho X^{*} Y\right]-\operatorname{Tr}\left[\rho^{1 / 2} X^{*} \rho^{1 / 2} Y\right]
$$

for any operators $X$ and $Y$. This result refined the Heisenberg-type uncertainty relation (4) shown in [18] for mixed states (general states). We easily find that the inequality (6) is equivalent to the following inequality:

$$
\begin{equation*}
U_{\rho}(A) U_{\rho}(B) \geq\left|\operatorname{Corr}_{\rho}(A, B)\right|^{2} \tag{7}
\end{equation*}
$$

The main purpose of this paper is to give some extensions of the inequality (7) by using the Wigner-Yanase-Dyson skew information $I_{\rho, \alpha}(H)$ and the metric adjusted correlation measure introduced in [12].

## 2 Schrödinger uncertainty relation with Wigner-Yanase-Dyson skew information

In this section, we give a generalization of the Schrödinger type uncertainty relation (7) by the use of the quantity $U_{\rho, \alpha}(H)$ defined by the Wigner-Yanase-Dyson skew information $I_{\rho, \alpha}(H)$.

Theorem 2.1 For $\alpha \in[1 / 2,1]$, a quantum state $\rho$ and two observables $A$ and $B$, we have

$$
\begin{equation*}
U_{\rho, \alpha}(A) U_{\rho, \alpha}(B) \geq 4 \alpha(1-\alpha)\left|\operatorname{Corr}_{\rho, \alpha}(A, B)\right|^{2} . \tag{8}
\end{equation*}
$$

where the generalized correlation measure $[14,36]$ is defined by

$$
\operatorname{Corr}_{\rho, \alpha}(X, Y) \equiv \operatorname{Tr}\left[\rho X^{*} Y\right]-\operatorname{Tr}\left[\rho^{\alpha} X^{*} \rho^{1-\alpha} Y\right]
$$

for any operators $X$ and $Y$.
To prove Theorem 2.1, we need the following lemmas.
Lemma 2.2 ([33]) For a spectral decomposition of $\rho=\sum_{j=1}^{\infty} \lambda_{j}\left|\phi_{j}\right\rangle\left\langle\phi_{j}\right|$, putting $h_{i j} \equiv\left\langle\phi_{i}\right| H_{0}\left|\phi_{j}\right\rangle$, we have the following relations.
(i) For the Wigner-Yanase-Dyson skew information, we have

$$
I_{\rho, \alpha}(H)=\sum_{i<j}\left(\lambda_{i}^{\alpha}-\lambda_{j}^{\alpha}\right)\left(\lambda_{i}^{1-\alpha}-\lambda_{j}^{1-\alpha}\right)\left|h_{i j}\right|^{2} .
$$

(ii) For the quantity associated to the Wigner-Yanase-Dyson skew information:

$$
J_{\rho, \alpha}(H) \equiv \frac{1}{2} \operatorname{Tr}\left[\left(\left\{\rho^{\alpha}, H_{0}\right\}\right)\left(\left\{\rho^{1-\alpha}, H_{0}\right\}\right)\right]=\operatorname{Tr}\left[\rho H_{0}^{2}\right]+\operatorname{Tr}\left[\rho^{\alpha} H_{0} \rho^{1-\alpha} H_{0}\right],
$$

where $\{X, Y\} \equiv X Y+Y X$ is an anti-commutator, we have

$$
J_{\rho, \alpha}(H) \geq \sum_{i<j}\left(\lambda_{i}^{\alpha}+\lambda_{j}^{\alpha}\right)\left(\lambda_{i}^{1-\alpha}+\lambda_{j}^{1-\alpha}\right)\left|h_{i j}\right|^{2} .
$$

Lemma 2.3 ([2, 33]) For any $t>0$ and $\alpha \in[0,1]$, we have

$$
(1-2 \alpha)^{2}(t-1)^{2} \geq\left(t^{\alpha}-t^{1-\alpha}\right)^{2}
$$

Proof of Theorem 2.1: We take a spectral decomposition $\rho=\sum_{j=1}^{\infty} \lambda_{j}\left|\phi_{j}\right\rangle\left\langle\phi_{j}\right|$. If we put $a_{i j}=\left\langle\phi_{i}\right| A_{0}\left|\phi_{j}\right\rangle$ and $b_{j i}=\left\langle\phi_{j}\right| B_{0}\left|\phi_{i}\right\rangle$, where $A_{0}=A-\operatorname{Tr}[\rho A] I$ and $B_{0}=B-\operatorname{Tr}[\rho B] I$, then we have

$$
\begin{align*}
\operatorname{Corr}_{\rho, \alpha}(A, B) & =\operatorname{Tr}[\rho A B]-\operatorname{Tr}\left[\rho^{\alpha} A \rho^{1-\alpha} B\right] \\
& =\operatorname{Tr}\left[\rho A_{0} B_{0}\right]-\operatorname{Tr}\left[\rho^{\alpha} A_{0} \rho^{1-\alpha} B_{0}\right] \\
& =\sum_{i, j=1}^{\infty}\left(\lambda_{i}-\lambda_{i}^{\alpha} \lambda_{j}^{1-\alpha}\right) a_{i j} b_{j i} \\
& =\sum_{i \neq j}\left(\lambda_{i}-\lambda_{i}^{\alpha} \lambda_{j}^{1-\alpha}\right) a_{i j} b_{j i} \\
& =\sum_{i<j}\left\{\left(\lambda_{i}-\lambda_{i}^{\alpha} \lambda_{j}^{1-\alpha}\right) a_{i j} b_{j i}+\left(\lambda_{j}-\lambda_{j}^{\alpha} \lambda_{i}^{1-\alpha}\right) a_{j i} b_{i j}\right\} . \tag{9}
\end{align*}
$$

Thus we have

$$
\left|\operatorname{Corr}_{\rho, \alpha}(A, B)\right| \leq \sum_{i<j}\left\{\left|\lambda_{i}-\lambda_{i}^{\alpha} \lambda_{j}^{1-\alpha}\right|\left|a_{i j}\right|\left|b_{j i}\right|+\left|\lambda_{j}-\lambda_{j}^{\alpha} \lambda_{i}^{1-\alpha}\right|\left|a_{j i}\right|\left|b_{i j}\right|\right\} .
$$

Since $\left|a_{i j}\right|=\left|a_{j i}\right|$ and $\left|b_{i j}\right|=\left|b_{j i}\right|$, taking a square of both sides and then using Schwarz inequality and Lemma 2.2, we have

$$
\begin{aligned}
& 4 \alpha(1-\alpha)\left|\operatorname{Corr}_{\rho, \alpha}(A, B)\right|^{2} \\
& \leq 4 \alpha(1-\alpha)\left\{\sum_{i<j}\left\{\left|\lambda_{i}-\lambda_{i}^{\alpha} \lambda_{j}^{1-\alpha}\right|+\left|\lambda_{j}-\lambda_{j}^{\alpha} \lambda_{i}^{1-\alpha}\right|\right\}\left|a_{i j}\right|\left|b_{j i}\right|\right\}^{2} \\
& =\left\{\sum_{i<j} 2 \sqrt{\alpha(1-\alpha)}\left(\lambda_{i}^{\alpha}+\lambda_{j}^{\alpha}\right)\left|\lambda_{i}^{1-\alpha}-\lambda_{j}^{1-\alpha}\right|\left|a_{i j}\right|\left|b_{j i}\right|\right\}^{2} \\
& \leq\left\{\sum_{i<j} 2 \sqrt{\alpha(1-\alpha)}\left|\lambda_{i}-\lambda_{j}\right|\left|a_{i j}\right|\left|b_{j i}\right|\right\}^{2} \\
& \leq\left\{\sum_{i<j}\left\{\left(\lambda_{i}^{\alpha}-\lambda_{j}^{\alpha}\right)\left(\lambda_{i}^{1-\alpha}-\lambda_{j}^{1-\alpha}\right)\left(\lambda_{i}^{\alpha}+\lambda_{j}^{\alpha}\right)\left(\lambda_{i}^{1-\alpha}+\lambda_{j}^{1-\alpha}\right)\right\}^{1 / 2}\left|a_{i j}\right|\left|b_{j i}\right|\right\}^{2} \\
& \leq\left\{\sum_{i<j}\left(\lambda_{i}^{\alpha}-\lambda_{j}^{\alpha}\right)\left(\lambda_{i}^{1-\alpha}-\lambda_{j}^{1-\alpha}\right)\left|a_{i j}\right|^{2}\right\}\left\{\sum_{i<j}\left(\lambda_{i}^{\alpha}+\lambda_{j}^{\alpha}\right)\left(\lambda_{i}^{1-\alpha}+\lambda_{j}^{1-\alpha}\right)\left|b_{i j}\right|^{2}\right\} \\
& \leq I_{\rho, \alpha}(A) J_{\rho, \alpha}(B)
\end{aligned}
$$

In the above process, the inequality $\left(x^{\alpha}+y^{\alpha}\right)\left|x^{1-\alpha}-y^{1-\alpha}\right| \leq|x-y|$ for $x, y \geq 0$ and $\alpha \in\left[\frac{1}{2}, 1\right]$ and the inequality $4 \alpha(1-\alpha)(x-y)^{2} \leq\left(x^{\alpha}-y^{\alpha}\right)\left(x^{1-\alpha}-y^{1-\alpha}\right)\left(x^{\alpha}+y^{\alpha}\right)\left(x^{1-\alpha}+y^{1-\alpha}\right)$ for $x, y \geq 0$ and $\alpha \in[0,1]$, which can be proven by Lemma 2.3, were used. By the similar way, we also have

$$
4 \alpha(1-\alpha)\left|\operatorname{Cor}_{\rho, \alpha}(A, B)\right|^{2} \leq I_{\rho, \alpha}(B) J_{\rho, \alpha}(A) .
$$

Thus for $\alpha \geq \frac{1}{2}$ we have

$$
\begin{equation*}
4 \alpha(1-\alpha)\left|\operatorname{Corr}_{\rho, \alpha}(A, B)\right|^{2} \leq U_{\rho, \alpha}(A) U_{\rho, \alpha}(B) . \tag{10}
\end{equation*}
$$

Note that Theorem 2.1 recovers the inequality (7), if we take $\alpha=\frac{1}{2}$.

Remark 2.4 We take $\alpha=0.1$ and

$$
\rho=\frac{1}{3}\left(\begin{array}{ll}
1 & 0 \\
0 & 2
\end{array}\right), A=\left(\begin{array}{cc}
2 & 2-i \\
2+i & 1
\end{array}\right), B=\left(\begin{array}{cc}
2 & i \\
-i & 1
\end{array}\right),
$$

then we have

$$
U_{\rho, \alpha}(A) U_{\rho, \alpha}(B)-4 \alpha(1-\alpha)\left|\operatorname{Corr}_{\rho, \alpha}(A, B)\right|^{2} \simeq-0.28332
$$

Therefore the inequality (8) does not hold for $\alpha \in[0,1 / 2)$ in general.
Corollary 2.5 Under the same assumptions with Theorem 2.1, we have the following inequality:

$$
\begin{align*}
U_{\rho, \alpha}(A) U_{\rho, \alpha}(B)- & 4 \alpha(1-\alpha)\left(\left|\operatorname{Re}\left\{\operatorname{Cor}_{\rho, \alpha}(A, B)\right\}\right|^{2}-\left|\operatorname{Im}\left\{\operatorname{Tr}\left[\rho^{\alpha} A \rho^{1-\alpha} B\right]\right\}\right|^{2}\right) \\
& \geq \alpha(1-\alpha)|\operatorname{Tr}[\rho[A, B]]|^{2} . \tag{11}
\end{align*}
$$

Proof: From

$$
\operatorname{Im}\left\{\operatorname{Corr}_{\rho, \alpha}(A, B)\right\}=\frac{1}{2 i} \operatorname{Tr}[\rho[A, B]]-\operatorname{Im}\left\{\operatorname{Tr}\left[\rho^{\alpha} A \rho^{1-\alpha} B\right]\right\},
$$

we have

$$
\frac{1}{4}|\operatorname{Tr}[\rho[A, B]]|^{2} \leq\left|\operatorname{Im}\left\{\operatorname{Corr}_{\rho, \alpha}(A, B)\right\}\right|^{2}+\left|\operatorname{Im}\left\{\operatorname{Tr}\left[\rho^{\alpha} A \rho^{1-\alpha} B\right]\right\}\right|^{2} .
$$

Thus we have

$$
\begin{aligned}
\left|\operatorname{Corr}_{\rho, \alpha}(A, B)\right|^{2} & =\left|\operatorname{Re}\left\{\operatorname{Corr}_{\rho, \alpha}(A, B)\right\}\right|^{2}+\left|\operatorname{Im}\left\{\operatorname{Corr}_{\rho, \alpha}(A, B)\right\}\right|^{2} \\
& \geq\left|\operatorname{Re}\left\{\operatorname{Corr}_{\rho, \alpha}(A, B)\right\}\right|^{2}+\frac{1}{4}|\operatorname{Tr}[\rho[A, B]]|^{2}-\left|\operatorname{Im}\left\{\operatorname{Tr}\left[\rho^{\alpha} A \rho^{1-\alpha} B\right]\right\}\right|^{2},
\end{aligned}
$$

which proves the corollary.

Remark 2.6 The following inequality does not hold in general for $\alpha \in\left[\frac{1}{2}, 1\right]$ :

$$
\begin{equation*}
\left|\operatorname{Re}\left\{\operatorname{Corr}_{\rho, \alpha}(A, B)\right\}\right|^{2} \geq\left|\operatorname{Im}\left\{\operatorname{Tr}\left[\rho^{\alpha} A \rho^{1-\alpha} B\right]\right\}\right|^{2} . \tag{12}
\end{equation*}
$$

Because we have a counter-example as follows. We take $\alpha=\frac{2}{3}$ and

$$
\rho=\frac{1}{7}\left(\begin{array}{ll}
2 & 3 \\
3 & 5
\end{array}\right), A=\left(\begin{array}{cc}
2 & 2-i \\
2+i & 1
\end{array}\right), B=\left(\begin{array}{cc}
2 & i \\
-i & 1
\end{array}\right),
$$

then we have

$$
\left|\operatorname{Re}\left\{\operatorname{Corr}_{\rho, \alpha}(A, B)\right\}\right|^{2}-\left|\operatorname{Im}\left\{\operatorname{Tr}\left[\rho^{\alpha} A \rho^{1-\alpha} B\right]\right\}\right|^{2} \simeq-0.0548142 .
$$

This shows Theorem 2.1 does not refine the inequality (5) in general.

## 3 Two-parameter extensions

In this section, we introduce the parametric extended correlation measure $\operatorname{Corr}_{\rho, \alpha, \gamma}(X, Y)$ by the convex combination between $\operatorname{Corr}_{\rho, \alpha}(X, Y)$ and $\operatorname{Corr}_{\rho, 1-\alpha}(X, Y)$. Then we establish the parametric extended Schrödinger-type uncertainty relation applying the parametric extended correlation measure $\operatorname{Corr}_{\rho, \alpha, \gamma}(X, Y)$. In addition, introducing the symmetric extended correlation measure $\operatorname{Corr}_{\rho, \alpha, \gamma}^{(s y m)}(X, Y)$ by the convex combination between $\operatorname{Corr}_{\rho, \alpha}(X, Y)$ and $\operatorname{Corr}_{\rho, \alpha}(Y, X)$, we show its Schrödinger-type uncertainty relation.

Definition 3.1 We define the parametric extended correlation measure $\operatorname{Corr}_{\rho, \alpha, \gamma}(X, Y)$ for two parameters $\alpha, \gamma \in[0,1]$ by

$$
\begin{equation*}
\operatorname{Corr}_{\rho, \alpha, \gamma}(X, Y) \equiv \gamma \operatorname{Corr}_{\rho, \alpha}(X, Y)+(1-\gamma) \operatorname{Corr}_{\rho, 1-\alpha}(X, Y) \tag{13}
\end{equation*}
$$

for any operators $X$ and $Y$.
Note that we have $\operatorname{Corr}_{\rho, \alpha, \gamma}(H, H)=I_{\rho, \alpha}(H)$ for any observable $H$. Then we can prove the following inequality.

Theorem 3.2 If $0 \leq \alpha, \gamma \leq \frac{1}{2}$ or $\frac{1}{2} \leq \alpha, \gamma \leq 1$, then we have

$$
U_{\rho, \alpha}(A) U_{\rho, \alpha}(B) \geq 4 \alpha(1-\alpha)\left|\operatorname{Corr}_{\rho, \alpha, \gamma}(A, B)\right|^{2}
$$

for two observables $A, B$ and a quantum state $\rho$.
Proof: By the similar way of the proof of Theorem 2.1, we have Eq.(9) and we also have

$$
\begin{align*}
\operatorname{Corr}_{\rho, 1-\alpha}(A, B) & =\operatorname{Tr}[\rho A B]-\operatorname{Tr}\left[\rho^{1-\alpha} A \rho^{\alpha} B\right] \\
& =\sum_{i<j}\left\{\left(\lambda_{i}-\lambda_{i}^{1-\alpha} \lambda_{j}^{\alpha}\right) a_{i j} b_{j i}+\left(\lambda_{j}-\lambda_{j}^{1-\alpha} \lambda_{i}^{\alpha}\right) a_{j i} b_{i j}\right\} \tag{14}
\end{align*}
$$

Thus we have

$$
\begin{aligned}
\operatorname{Corr}_{\rho, \alpha, \gamma}(A, B)= & \gamma \operatorname{Corr}_{\rho, \alpha}(A, B)+(1-\gamma) \operatorname{Corr}_{\rho, \alpha}(A, B) \\
= & \sum_{i<j}\left\{\gamma \lambda_{i}^{\alpha}\left(\lambda_{i}^{1-\alpha}-\lambda_{j}^{1-\alpha}\right)+(1-\gamma) \lambda_{i}^{1-\alpha}\left(\lambda_{i}^{\alpha}-\lambda_{j}^{\alpha}\right)\right\} a_{i j} b_{j i} \\
& \quad+\sum_{i<j}\left\{\gamma \lambda_{j}^{\alpha}\left(\lambda_{j}^{1-\alpha}-\lambda_{i}^{1-\alpha}\right)+(1-\gamma) \lambda_{j}^{1-\alpha}\left(\lambda_{j}^{\alpha}-\lambda_{i}^{\alpha}\right)\right\} a_{j i} b_{i j} .
\end{aligned}
$$

Since we have $\left|a_{i j}\right|=\left|a_{j i}\right|$ and $\left|b_{i j}\right|=\left|b_{j i}\right|$, we then have

$$
\begin{aligned}
\left|\operatorname{Corr}_{\rho, \alpha, \gamma}(A, B)\right| & \leq \sum_{i<j}\left\{\gamma\left(\lambda_{i}^{\alpha}+\lambda_{j}^{\alpha}\right)\left|\lambda_{i}^{1-\alpha}-\lambda_{j}^{1-\alpha}\right|+(1-\gamma)\left(\lambda_{i}^{1-\alpha}+\lambda_{j}^{1-\alpha}\right)\left|\lambda_{i}^{\alpha}-\lambda_{j}^{\alpha}\right|\right\}\left|a_{i j} \|\left|b_{j i}\right|\right. \\
& \leq \sum_{i<j}\left|\lambda_{i}-\lambda_{j}\right|\left|a_{i j} \| b_{j i}\right|
\end{aligned}
$$

thanks to the inequality

$$
\begin{equation*}
\gamma\left(x^{\alpha}+y^{\alpha}\right)\left|x^{1-\alpha}-y^{1-\alpha}\right|+(1-\gamma)\left(x^{1-\alpha}+y^{1-\alpha}\right)\left|x^{\alpha}-y^{\alpha}\right| \leq|x-y| \tag{15}
\end{equation*}
$$

for $0 \leq \alpha, \gamma \leq \frac{1}{2}$ or $\frac{1}{2} \leq \alpha, \gamma \leq 1$, and $x, y \geq 0$. The rest of the proof goes similar way to that of Theorem 2.1.

Corollary 3.3 For any $\alpha \in[0,1]$, two observables $A, B$ and a quantum state $\rho$, we have

$$
U_{\rho, \alpha}(A) U_{\rho, \alpha}(B) \geq 4 \alpha(1-\alpha)\left|\operatorname{Corr}_{\rho, \alpha, \frac{1}{2}}(A, B)\right|^{2}
$$

Proof: If $\gamma=\frac{1}{2}$, then the equality of the inequality (15) holds for any $\alpha \in[0,1]$ and $x, y \geq 0$. Therefore we have the present corollary from Theorem 3.2.

We may define the following correlation measure instead of Definition 3.1.

Definition 3.4 We define a symmetric extended correlation measure $\operatorname{Corr}_{\rho, \alpha, \gamma}^{(s y m)}(X, Y)$ for two parameters $\alpha, \gamma \in[0,1]$ by

$$
\begin{equation*}
\operatorname{Corr}_{\rho, \alpha, \gamma}^{(s y m)}(X, Y) \equiv \gamma \operatorname{Corr}_{\rho, \alpha}(X, Y)+(1-\gamma) \operatorname{Corr}_{\rho, \alpha}(Y, X) \tag{16}
\end{equation*}
$$

for any operators $X$ and $Y$.
Note that we have $\operatorname{Corr}_{\rho, \alpha, \gamma}^{(s y m)}(A, B)=\operatorname{Corr}_{\rho, \alpha, \gamma}^{(s y m)}(B, A)$ for self-adjoint operators $A$ and $B$. Then we have the following therem by the similar proof of the above using the inequality

$$
\left(x^{\alpha}+y^{\alpha}\right)\left|x^{1-\alpha}-y^{1-\alpha}\right| \leq|x-y|
$$

for $x, y \geq 0$ and $\alpha \geq \frac{1}{2}$.
Theorem 3.5 For $\alpha \in\left[\frac{1}{2}, 1\right]$ and $\gamma \in[0,1]$, we have

$$
U_{\rho, \alpha}(A) U_{\rho, \alpha}(B) \geq 4 \alpha(1-\alpha)\left|\operatorname{Corr}_{\rho, \alpha, \gamma}^{(s y m)}(A, B)\right|^{2}
$$

for two observables $A, B$ and a quantum state $\rho$.

## 4 A further generalization by metric adjusted correlation measure

Inspired by the recent results in [10] and the concept of metric adjusted skew information introduced by Hansen in [12], we here give a further generalization for Schrödinger-type uncertainty relation applying metric adjusted correlation measure introduced in [12]. We firstly give some notations according to those in [10]. Let $M_{n}(\mathbb{C})$ and $M_{n, s a}(\mathbb{C})$ be the set of all $n \times n$ complex matrices and all $n \times n$ self-adjoint matrices, equipped with the Hilbert-Schmidt scalar product $\langle A, B\rangle=\operatorname{Tr}\left[A^{*} B\right]$, respectively. Let $M_{n,+}(\mathbb{C})$ be the set of all positive definite matrices of $M_{n, s a}(\mathbb{C})$ and $M_{n,+, 1}(\mathbb{C})$ be the set of all density matrices, that is

$$
M_{n,+, 1}(\mathbb{C}) \equiv\left\{\rho \in M_{n, s a}(\mathbb{C}) \mid \operatorname{Tr} \rho=1, \rho>0\right\} \subset M_{n,+}(\mathbb{C}) .
$$

Here $X \in M_{n,+}(\mathbb{C})$ means we have $\langle\phi| X|\phi\rangle \geq 0$ for any vector $|\phi\rangle \in \mathbb{C}^{n}$. In the study of quantum physics, we usually use a positive semidefinite matrix with a unit trace as a density operator $\rho$. In this section, we assume the invertibility of $\rho$.

A function $f:(0,+\infty) \rightarrow \mathbb{R}$ is said operator monotone if the inequalities $0 \leq f(A) \leq$ $f(B)$ hold for any $A, B \in M_{n, s a}(\mathbb{C})$ such that $0 \leq A \leq B$. An operator monotone function $f:(0,+\infty) \rightarrow(0,+\infty)$ is said symmetric if $f(x)=x f\left(x^{-1}\right)$ and normalized if $f(1)=1$. We represents the set of all symmetric normalized operator monotone functions by $\mathcal{F}_{o p}$. We have the following examples as elements of $\mathcal{F}_{o p}$ :

Example 4.1 ([12, 10, 6, 25])

$$
\begin{gathered}
f_{R L D}(x)=\frac{2 x}{x+1}, \quad f_{S L D}(x)=\frac{x+1}{2}, \quad f_{B K M}(x)=\frac{x-1}{\log x}, \\
f_{W Y}(x)=\left(\frac{\sqrt{x}+1}{2}\right)^{2}, \quad f_{W Y D}(x)=\alpha(1-\alpha) \frac{(x-1)^{2}}{\left(x^{\alpha}-1\right)\left(x^{1-\alpha}-1\right)}, \alpha \in(0,1) .
\end{gathered}
$$

The functions $f_{B K M}(x)$ and $f_{W Y D}(x)$ are normalized in the sense that $\lim _{x \rightarrow 1} f_{B K M}(x)=1$ and $\lim _{x \rightarrow 1} f_{W Y D}(x)=1$. Note that a simple proof of the operator monotonicity of $f_{W Y D}(x)$ was given in [6]. See also [30] for the proof of the operator monotonicity of $f_{W Y D}(x)$ by use of majorization.

Remark $4.2([\mathbf{1 0}, \mathbf{1 5}, \mathbf{2 4}, \mathbf{2 5}])$ For any $f \in \mathcal{F}_{\text {op }}$, we have the following inequalities:

$$
\frac{2 x}{x+1} \leq f(x) \leq \frac{x+1}{2}, x>0
$$

That is, all $f \in \mathcal{F}_{\text {op }}$ lies in between the harmonic mean and the arithmetic mean.
For $f \in \mathcal{F}_{o p}$ we define $f(0)=\lim _{x \rightarrow 0} f(x)$. We also denote the sets of regular and non-regular functions by

$$
\mathcal{F}_{o p}^{r}=\left\{f \in \mathcal{F}_{o p} \mid f(0) \neq 0\right\} \text { and } \mathcal{F}_{o p}^{n}=\left\{f \in \mathcal{F}_{o p} \mid f(0)=0\right\} .
$$

Definition $4.3([8,10])$ For $f \in \mathcal{F}_{o p}^{r}$, we define the function $\tilde{f}$ by

$$
\tilde{f}(x)=\frac{1}{2}\left\{(x+1)-(x-1)^{2} \frac{f(0)}{f(x)}\right\}, \quad(x>0) .
$$

Then we have the following theorem.
Theorem $4.4([8,6,26])$ The correspondence $f \rightarrow \tilde{f}$ is a bijection between $\mathcal{F}_{o p}^{r}$ and $\mathcal{F}_{o p}^{n}$.
We can use matrix mean theory introduced by Kubo-Ando in [15]. Then a mean $m_{f}$ corresponds to each operator monotone function $f \in \mathcal{F}_{o p}$ by the following formula

$$
m_{f}(A, B)=A^{1 / 2} f\left(A^{-1 / 2} B A^{-1 / 2}\right) A^{1 / 2}
$$

for $A, B \in M_{n,+}(\mathbb{C})$. By the notion of matrix mean, we may define the set of the monotone metrics [23] by the following formula

$$
\langle A, B\rangle_{\rho, f}=\operatorname{Tr}\left[A m_{f}\left(L_{\rho}, R_{\rho}\right)^{-1}(B)\right],
$$

where $L_{\rho}(A)=\rho A$ and $R_{\rho}(A)=A \rho$.
Definition $4.5([12,8])$ For $A, B \in M_{n, s a}(\mathbb{C}), \rho \in M_{n,+, 1}(\mathbb{C})$ and $f \in \mathcal{F}_{\text {op }}^{r}$, we define the following quantities:

$$
\begin{aligned}
& \operatorname{Corr}_{\rho}^{f}(A, B) \equiv \frac{f(0)}{2}\langle i[\rho, A], i[\rho, B]\rangle_{\rho, f}, I_{\rho}^{f}(A) \equiv \operatorname{Corr}_{\rho}^{f}(A, A), \\
& C_{\rho}^{f}(A, B) \equiv \operatorname{Tr}\left[m_{f}\left(L_{\rho}, R_{\rho}\right)(A) B\right], C_{\rho}^{f}(A) \equiv C_{\rho}^{f}(A, A), \\
& U_{\rho}^{f}(A) \equiv \sqrt{V_{\rho}(A)^{2}-\left(V_{\rho}(A)-I_{\rho}^{f}(A)\right)^{2}} .
\end{aligned}
$$

The quantity $I_{\rho}^{f}(A)$ is known as metric adjusted skew information [12]. It is notable that the metric adjusted correlation measure $\operatorname{Corr}_{\rho}^{c}(A, B)$ was firstly introduced in [12] for a regular Morozova-Chentsov function $c$. Recently the notation $I_{\rho}^{c}(A, B)$ in $[1]$ and the notation $I_{\rho}^{f}(A, B)$ in [11] were used. In addition, it is useful for the readers to be noted that the correlation $I_{\rho}^{f}(A, B)$ can be expressed as a difference of covariances [11]. Throughout the present paper, we use the notation $\operatorname{Corr}_{\rho}^{f}(A, B)$ as the metric adjusted correlation measure, to avoid the confusion of the readers. (In the previous sections, we have already used $\operatorname{Corr}_{\rho}(A, B), \operatorname{Corr}_{\rho, \alpha}(A, B)$ and $\operatorname{Corr}_{\rho, \alpha, \gamma}(A, B)$ as correlation measures and done $I_{\rho}(H)$ and $I_{\rho, \alpha}(H)$ as skew informations.) Then we have the following proposition.

Proposition $4.6([8,10])$ For $A, B \in M_{n, s a}(\mathbb{C}), \rho \in M_{n,+, 1}(\mathbb{C})$ and $f \in \mathcal{F}_{\text {op }}^{r}$, we have the following relations, where we put $A_{0} \equiv A-\operatorname{Tr}[\rho A] I$ and $B_{0} \equiv B-\operatorname{Tr}[\rho B] I$.
(1) $I_{\rho}^{f}(A)=\operatorname{Tr}\left[\rho A_{0}^{2}\right]-\operatorname{Tr}\left[m_{\tilde{f}}\left(L_{\rho}, R_{\rho}\right)\left(A_{0}\right) A_{0}\right]=V_{\rho}(A)-C_{\rho}^{\tilde{f}}\left(A_{0}\right)$.
(2) $J_{\rho}^{f}(A)=\operatorname{Tr}\left[\rho A_{0}^{2}\right]+\operatorname{Tr}\left[m_{\tilde{f}}\left(L_{\rho}, R_{\rho}\right)\left(A_{0}\right) A_{0}\right]=V_{\rho}(A)+C_{\rho}^{\tilde{f}}\left(A_{0}\right)$.
(3) $0 \leq I_{\rho}^{f}(A) \leq U_{\rho}^{f}(A) \leq V_{\rho}(A)$.
(4) $U_{\rho}^{f}(A)=\sqrt{I_{\rho}^{f}(A) J_{\rho}^{f}(A)}$.
(5) $\operatorname{Corr}_{\rho}^{f}(A, B)=\frac{1}{2} \operatorname{Tr}\left[\rho A_{0} B_{0}\right]+\frac{1}{2} \operatorname{Tr}\left[\rho B_{0} A_{0}\right]-\operatorname{Tr}\left[m_{\tilde{f}}\left(L_{\rho}, R_{\rho}\right)\left(A_{0}\right) B_{0}\right]=\frac{1}{2} \operatorname{Tr}\left[\rho A_{0} B_{0}\right]+$ $\frac{1}{2} \operatorname{Tr}\left[\rho B_{0} A_{0}\right]-C_{\rho}^{\tilde{f}}\left(A_{0}, B_{0}\right)$.
The following inequality is the further generalization of Corollary 3.3 by the use of the metric adjusted correlation measure.

Theorem 4.7 For $f \in \mathcal{F}_{o p}^{r}$, if we have

$$
\begin{equation*}
\frac{x+1}{2}+\tilde{f}(x) \geq 2 f(x) \tag{17}
\end{equation*}
$$

then we have

$$
\begin{equation*}
U_{\rho}^{f}(A) U_{\rho}^{f}(B) \geq 4 f(0)\left|\operatorname{Corr}_{\rho}^{f}(A, B)\right|^{2}, \tag{18}
\end{equation*}
$$

for $A, B \in M_{n, s a}(\mathbb{C})$ and $\rho \in M_{n,+, 1}(\mathbb{C})$.
In order to prove Theorem 4.7, we use the following two lemmas.
Lemma 4.8 ([35]) If Eq.(17) is satisfied, then we have the following inequality:

$$
\left(\frac{x+y}{2}\right)^{2}-m_{\tilde{f}}(x, y)^{2} \geq f(0)(x-y)^{2}
$$

Proof: By Eq.(17), we have

$$
\frac{x+y}{2}+m_{\tilde{f}}(x, y) \geq 2 m_{f}(x, y)
$$

We also have

$$
\begin{aligned}
m_{\tilde{f}}(x, y) & =y \tilde{f}\left(\frac{x}{y}\right) \\
& =\frac{y}{2}\left\{\frac{x}{y}+1-\left(\frac{x}{y}-1\right)^{2} \frac{f(0)}{f(x / y)}\right\} \\
& =\frac{x+y}{2}-\frac{f(0)(x-y)^{2}}{2 m_{f}(x, y)}
\end{aligned}
$$

Therefore

$$
\begin{aligned}
\left(\frac{x+y}{2}\right)^{2}-m_{\tilde{f}}(x, y)^{2} & =\left\{\frac{x+y}{2}-m_{\tilde{f}}(x, y)\right\}\left\{\frac{x+y}{2}+m_{\tilde{f}}(x, y)\right\} \\
& \geq \frac{f(0)(x-y)^{2}}{2 m_{f}(x, y)} 2 m_{f}(x, y) \\
& =f(0)(x-y)^{2}
\end{aligned}
$$

We have the following expressions for the quantities $I_{\rho}^{f}(A), J_{\rho}^{f}(A), U_{\rho}^{f}(A)$ and $\operatorname{Corr}_{\rho}^{f}(A, B)$ by using Proposition 4.6 and a mean $m_{\tilde{f}}$.

Lemma 4.9 ([10]) Let $\left\{\left|\phi_{1}\right\rangle,\left|\phi_{2}\right\rangle, \cdots,\left|\phi_{n}\right\rangle\right\}$ be a basis of eigenvectors of $\rho$, corresponding to the eigenvalues $\left\{\lambda_{1}, \lambda_{2}, \cdots, \lambda_{n}\right\}$. We put $a_{j k}=\left\langle\phi_{j}\right| A_{0}\left|\phi_{k}\right\rangle, b_{j k}=\left\langle\phi_{j}\right| B_{0}\left|\phi_{k}\right\rangle$, where $A_{0} \equiv A-$ $\operatorname{Tr}[\rho A] I$ and $B_{0} \equiv B-\operatorname{Tr}[\rho B] I$ for $A, B \in M_{n, s a}(\mathbb{C})$ and $\rho \in M_{n,+, 1}(\mathbb{C})$. Then we have

$$
\begin{aligned}
I_{\rho}^{f}(A) & =\frac{1}{2} \sum_{j, k}\left(\lambda_{j}+\lambda_{k}\right) a_{j k} a_{k j}-\sum_{j, k} m_{\tilde{f}}\left(\lambda_{j}, \lambda_{k}\right) a_{j k} a_{k j} \\
& =2 \sum_{j<k}\left\{\frac{\lambda_{j}+\lambda_{k}}{2}-m_{\tilde{f}}\left(\lambda_{j}, \lambda_{k}\right)\right\}\left|a_{j k}\right|^{2} \\
J_{\rho}^{f}(A) & =\frac{1}{2} \sum_{j, k}\left(\lambda_{j}+\lambda_{k}\right) a_{j k} a_{k j}+\sum_{j, k} m_{\tilde{f}}\left(\lambda_{j}, \lambda_{k}\right) a_{j k} a_{k j} \\
& \geq 2 \sum_{j<k}\left\{\frac{\lambda_{j}+\lambda_{k}}{2}+m_{\tilde{f}}\left(\lambda_{j}, \lambda_{k}\right)\right\}\left|a_{j k}\right|^{2} \\
U_{\rho}^{f}(A)^{2}= & \frac{1}{4}\left(\sum_{j, k}\left(\lambda_{j}+\lambda_{k}\right)\left|a_{j k}\right|^{2}\right)^{2}-\left(\sum_{j, k} m_{\tilde{f}}\left(\lambda_{j}, \lambda_{k}\right)\left|a_{j k}\right|^{2}\right)^{2}
\end{aligned}
$$

and

$$
\begin{align*}
\operatorname{Corr}_{\rho}^{f}(A, B) & =\frac{1}{2} \sum_{j, k} \lambda_{j} a_{j k} b_{k j}+\frac{1}{2} \sum_{j, k} \lambda_{k} a_{j k} b_{k j}-\sum_{j, k} m_{\tilde{f}}\left(\lambda_{j}, \lambda_{k}\right) a_{j k} b_{k j} \\
& =\sum_{j<k}\left(\frac{\lambda_{j}+\lambda_{k}}{2}-m_{\tilde{f}}\left(\lambda_{j}, \lambda_{k}\right)\right) a_{j k} b_{k j}+\sum_{j<k}\left(\frac{\lambda_{k}+\lambda_{j}}{2}-m_{\tilde{f}}\left(\lambda_{k}, \lambda_{j}\right)\right) a_{k j} b_{j k} . \tag{19}
\end{align*}
$$

We are now in a position to prove Theorem 4.7.
Proof of Theorem 4.7: From Eq.(19), we have

$$
\begin{aligned}
\left|\operatorname{Corr}_{\rho}^{f}(A, B)\right| & \leq \sum_{j<k}\left|\left(\frac{\lambda_{j}+\lambda_{k}}{2}-m_{\tilde{f}}\left(\lambda_{j}, \lambda_{k}\right)\right) a_{j k} b_{k j}\right|+\sum_{j<k}\left|\left(\frac{\lambda_{j}+\lambda_{k}}{2}-m_{\tilde{f}}\left(\lambda_{k}, \lambda_{j}\right)\right) a_{k j} b_{j k}\right| \\
& \leq \sum_{j<k}\left|\frac{\lambda_{j}+\lambda_{k}}{2}-m_{\tilde{f}}\left(\lambda_{j}, \lambda_{k}\right)\right|\left|a_{j k}\right|\left|b_{k j}\right|+\sum_{j<k}\left|\frac{\lambda_{j}+\lambda_{k}}{2}-m_{\tilde{f}}\left(\lambda_{k}, \lambda_{j}\right)\right|\left|a_{k j}\right|\left|b_{j k}\right| \\
& =2 \sum_{j<k}\left|\frac{\lambda_{j}+\lambda_{k}}{2}-m_{\tilde{f}}\left(\lambda_{j}, \lambda_{k}\right)\right|\left|a_{j k}\right|\left|b_{k j}\right| \\
& \leq \sum_{j<k}\left|\lambda_{j}-\lambda_{k}\right|\left|a_{j k}\right|\left|b_{k j}\right| .
\end{aligned}
$$

Then we have

$$
f(0)\left|\operatorname{Corr}_{\rho}^{f}(A, B)\right|^{2} \leq\left(\sum_{j<k} f(0)^{1 / 2}\left|\lambda_{j}-\lambda_{k}\right|\left|a_{j k}\right|\left|b_{k j}\right|\right)^{2}
$$

$$
\begin{aligned}
\leq & \left(\sum_{j<k}\left\{\left(\frac{\lambda_{j}+\lambda_{k}}{2}\right)^{2}-m_{\tilde{f}}\left(\lambda_{j}, \lambda_{k}\right)^{2}\right\}^{1 / 2}\left|a_{j k}\right|\left|b_{k j}\right|\right)^{2} \\
\leq & \left(\sum_{j<k}\left\{\frac{\lambda_{j}+\lambda_{k}}{2}-m_{\tilde{f}}\left(\lambda_{j}, \lambda_{k}\right)\right\}\left|a_{j k}\right|^{2}\right) \\
& \times\left(\sum_{j<k}\left\{\frac{\lambda_{j}+\lambda_{k}}{2}+m_{\tilde{f}}\left(\lambda_{j}, \lambda_{k}\right)\right\}\left|b_{k j}\right|^{2}\right) \\
\leq & \frac{1}{4} I_{\rho}^{f}(A) J_{\rho}^{f}(B) .
\end{aligned}
$$

By the similar way, we also have

$$
I_{\rho}^{f}(B) J_{\rho}^{f}(A) \geq 4 f(0)\left|\operatorname{Corr}_{\rho}^{f}(A, B)\right|^{2}
$$

Hence we have the desired inequality (18).

Remark 4.10 Under the same assumptions with Theorem 4.7, we have the following Heisenbergtype uncertainty relation [35]:

$$
\begin{equation*}
U_{\rho}^{f}(A) U_{\rho}^{f}(B) \geq f(0)|\operatorname{Tr}[\rho[A, B]]|^{2} \tag{20}
\end{equation*}
$$

by the similar way to the proof of Theorem 4.7, since we have

$$
|\operatorname{Tr}[\rho[A, B]]| \leq 2 \sum_{j<k}\left|\lambda_{j}-\lambda_{k}\right|\left|a_{j k}\right|\left|b_{k j}\right|
$$

As stated in Remark 2.6, there is no ordering between the right hand side of the inequality (18) and that of the inequality (20), in general.

If we use the function

$$
f_{W Y D}(x)=\alpha(1-\alpha) \frac{(x-1)^{2}}{\left(x^{\alpha}-1\right)\left(x^{1-\alpha}-1\right)}, \quad \alpha \in(0,1)
$$

then we obtain the following uncertainty relation.
Corollary 4.11 For $A, B \in M_{n, s a}(\mathbb{C})$ and $\rho \in M_{n,+, 1}(\mathbb{C})$, we have

$$
U_{\rho}^{f_{W Y D}}(A) U_{\rho}^{f_{W Y D}}(B) \geq 4 \alpha(1-\alpha)\left|\operatorname{Corr}_{\rho}^{f_{W Y D}}(A, B)\right|^{2}
$$

Proof: From the definition

$$
f_{W Y D}(x)=\alpha(1-\alpha) \frac{(x-1)^{2}}{\left(x^{\alpha}-1\right)\left(x^{1-\alpha}-1\right)}
$$

it is clear that

$$
\tilde{f}_{W Y D}(x)=\frac{1}{2}\left\{x+1-\left(x^{\alpha}-1\right)\left(x^{1-\alpha}-1\right)\right\}
$$

By Lemma 2.3, we have for $0 \leq \alpha \leq 1$ and $x>0$,

$$
(1-2 \alpha)^{2}(x-1)^{2}-\left(x^{\alpha}-x^{1-\alpha}\right)^{2} \geq 0
$$

This inequality can be rewritten by

$$
\left(x^{2 \alpha}-1\right)\left(x^{2(1-\alpha)}-1\right) \geq 4 \alpha(1-\alpha)(x-1)^{2} .
$$

Thus we have

$$
\begin{aligned}
\frac{x+1}{2}+\tilde{f}_{W Y D}(x) & =x+1-\frac{1}{2}\left(x^{\alpha}-1\right)\left(x^{1-\alpha}-1\right) \\
& =\frac{1}{2}\left(x^{\alpha}+1\right)\left(x^{1-\alpha}+1\right) \\
& \geq 2 \alpha(1-\alpha) \frac{(x-1)^{2}}{\left(x^{\alpha}-1\right)\left(x^{1-\alpha}-1\right)} \\
& =2 f_{W Y D}(x) .
\end{aligned}
$$

Thus we obtain the aimed result from Theorem 4.7.
Note that Corollary 3.3 coincides with Corollary 4.11, since we have $U_{\rho, \alpha}(A)=U_{\rho}^{f_{W Y D}}(A)$ which is obtained by the fact the function $f_{W Y D}(x)$ corresponds to the Wigner-Yanase-Dyson skew information. We also note that we have $\operatorname{Corr}_{\rho}^{f_{W Y D}}(A, B)=\operatorname{Corr}_{\rho, \alpha, \frac{1}{2}}^{(\text {sym })}(A, B)$ and $\operatorname{Corr}_{\rho}^{f_{W Y D}}(A, B) \neq \operatorname{Corr}_{\rho, \alpha, \frac{1}{2}}(A, B)$ in general.

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